### PAIENT COOPERATION TREATY

.ne :RNATIONAL PRELIMINARY EXAMINING AUTHORITY

o:

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15.07.2004

PCI

NOTIFICATION OF TRANSMITTAL OF THE INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

(PCT Rule 71.1)

Date of mailing

(day/month/year)

05.10.2005

Applicant's or agent's file reference A3232.WO.209

International application No. PCT/B2004/002330

International filing date (day/month/year)

Priority date (day/month/year)

17.07.2003

IMPORTANT NOTIFICATION

Applicant

AZIONARIA COSTRUZIONI MACCHINE AUTOMATICHE...

- 1. The applicant is hereby notified that this International Preliminary Examining Authority transmits herewith the international preliminary report on patentability and its annexes, if any, established on the international application.
- 2. A copy of the report and its annexes, if any, is being transmitted to the International Bureau for communication to all the elected Offices.
- 3. Where required by any of the elected Offices, the International Bureau will prepare an English translation of the report (but not of any annexes) and will transmit such translation to those Offices.

#### 4. REMINDER

The applicant must enter the national phase before each elected Office by performing certain acts (filing translations and paying national fees) within 30 months from the priority date (or later in some Offices) (Article 39(1)) (see also the reminder sent by the International Bureau with Form PCT/IB/301).

Where a translation of the international application must be furnished to an elected Office, that translation must contain a translation of any annexes to the international preliminary report on patentability. It is the applicant's responsibility to prepare and furnish such translation directly to each elected Office concerned.

For further details on the applicable time limits and requirements of the elected Offices, see Volume II of the PCT Applicant's Guide.

The applicant's attention is drawn to Article 33(5), which provides that the criteria of novelty, inventive step and industrial applicability described in Article 33(2) to (4) merely serve the purposes of international preliminary examination and that "any Contracting State may apply additional or different criteria for the purposes of deciding whether, in that State, the claimed inventions is patentable or not" (see also Article 27(5)). Such additional criteria may relate, for example, to exemptions from patentability, requirements for enabling disclosure, clarity and support for the claims.

Name and mailing address of the international preliminary examining authority:

<u>)</u>

European Patent Office - P.B. 5818 Patentlaan 2 NL-2280 HV Rijswijk - Pays Bas Tel. +31 70 340 - 2040 Tx: 31 651 epo nl Fax: +31 70 340 - 3016 Authorized Officer

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### PATENT COOPERATION TREATY

## **PCT**

## INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

(Chapter II of the Patent Cooperation Treaty)

(PCT Article 36 and Rule 70)

Applicant's or agent's file reference				
A3232.WO.209	FOR FURTHER ACTION	See Form PCT/IPEA/416		
International application No. PCT/IB2004/002330	International filing date (day/month/year 15.07.2004	Priority date (day/month/year) 17.07.2003		
International Patent Classification (IPC) or nat	ional classification and IPC			
B67B3/20, B67B3/28				
Applicant				
AZIONARIA COSTRUZIONI MACCH	IINE AUTOMATICHE			
The state of the s	mitted to the applicant according to			
2. This REPORT consists of a total of 5 sheets, including this cover sheet.				
This report is also accompanied by ANNEXES, comprising:				
a. Sent to the applicant and to t	<i>he International Bureau)</i> a total of 6	S sheets, as follows:		
<ul> <li>sheets of the description and/or sheets containing Administrative Instruction</li> </ul>		re been amended and are the basis of this report thority (see Rule 70.16 and Section 607 of the		
sheets which supersede beyond the disclosure in Supplemental Box.	earlier sheets, but which this Author the international application as filed	ority considers contain an amendment that goes d, as indicated in item 4 of Box No. I and the		
b. 🛘 (sent to the International Burn	eau only) a total of (indicate type ar	nd number of electronic carrier(s)), containing a		
	s related thereto, in computer reada sting (see Section 802 of the Admin			
- '	5 (199 9 9 9 8 8 9 9 1 1 1 1 1 1 1 1 1 1 1	isuative histractions).		
<ol> <li>This report contains indications relat</li> </ol>	ing to the following items:			
Box No. I Basis of the opinio	n			
☐ Box No. II Priority	•			
Box No. III Non-establishment	of opinion with regard to novelty, ir	nventive step and industrial applicability		
Lack of unity of inv	ention			
apphoability, citatio	ing and explanations supporting suc	o novelty, inventive step or industrial		
☐ Box No. VI Certain documents	cited			
	he international application			
☐ Box No. VIII Certain observation	is on the international application			
Date of submission of the demand	Date of comple	tion of this report		
13.05.2005				
	05.10.2005			
lame and mailing address of the international reliminary examining authority:	Authorized Office	cer		
European Patent Office - P.B. 5818 Patentiaan 2				
NL-2280 HV Hijswijk - Pays Bas Tel. +31 70 340 - 2040 Tx: 31 651	AA/amkamba	, F		
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# INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

International application No. PCT/IB2004/002330

_	Box No. I	Basis of the report
<ol> <li>With regard to the language, this report is based on the international application in the language, this report is based on the international application in the language, this report is based on the international application in the language.</li> </ol>		I to the <b>language</b> , this report is based on the international application in the language in which it was otherwise indicated under this item.
	☐ This rep	port is based on translations from the original language into the following language, s the language of a translation furnished for the purposes of:
	☐ publ	rnational search (under Rules 12.3 and 23.1(b)) lication of the international application (under Rule 12.4) rnational preliminary examination (under Rules 55.2 and/or 55.3)
ż.	With regard to the <b>elements*</b> of the international application, this report is based on <i>(replacement sheets which have been furnished to the receiving Office in response to an invitation under Article 14 are referred to in this report as "originally filed" and are not annexed to this report):</i>	
	Description,	, Pages
	1-19	as originally filed
Claims, Numbers		nbers
	1-13	received on 13.05.2005 with letter of 13.05.2005
*	Drawings, S	heets
	1/6-6/6	as originally filed
	□ a seque	ence listing and/or any related table(s) - see Supplemental Box Relating to Sequence Listing
3.	☐ The am	nendments have resulted in the cancellation of:
		description, pages claims, Nos. 14-17
	☐ the o	drawings, sheets/ligs sequence listing (specify):
		table(s) related to sequence listing (specify):
4.	had not bee	port has been established as if (some of) the amendments annexed to this report and listed below en made, since they have been considered to go beyond the disclosure as filed, as indicated in the tal Box (Rule 70.2(c)).
		description, pages claims, Nos.
	☐ the o	drawings, sheets/ligs
		sequence listing (specify): table(s) related to sequence listing (specify):
	* If ite	em 4 applies, some or all of these sheets may be marked "superseded."

Box No. V Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement

1. Statement

Novelty (N)

Yes: Claims

1-13

No:

Claims

Inventive step (IS)

Yes: Claims

1-13

No: Claims

Industrial applicability (IA)

Yes: Claims

1-13

No: Claims

2. Citations and explanations (Rule 70.7):

see separate sheet

### Re Item V

Reasoned statement with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement

Reference is made to the following document:

D1: US-A-4 535 583 (MURANAKA SHIARU ET AL) 20 August 1985 (1985-08-20)

### 1 INDEPENDENT CLAIM 1

- 1.1 The document D1 is regarded as being the closest prior art to the subject-matter of claim 1, and shows (the references in parentheses applying to this document):

  A capping unit comprising a conveyor (10), a motor (8), capping assemblies provided with gripping mechanisms (13), primary drive means (15, 16) setting a capping assembly in vertical motion and secondary drive means (12) connected to an electronic control device (19) setting a gripping mechanism in rotational motion.
- 1.2 The subject-matter of claim 1 differs from this known capping unit in that the primary drive means comprises an electric motor connected to the electronic control device, and in that the electronic controller comprises a processing block by means of which to vary the operating parameters of each primary and secondary electric motor according to the dimensions of the respective containers.

The subject-matter of claim 1 is therefore new (Article 33(2) PCT).

- 1.3 The problem to be solved by the present invention may be regarded as rendering the capping unit versatile and suitable for use with many types of containers irrespective of their size.
- 1.4 The solution to this problem proposed in claim 1 of the present application is considered as involving an inventive step (Article 33(3) PCT) for the following reasons:
  - The processing block of the controller provides the possibility to control the primary and secondary electric motors of each capping assembly independently, by means of the operating parameters, according to the dimensions of the containers, therewith, making the capping unit suitable to be used with any type of container.

### 2 DEPENDENT CLAIMS 2-13

Claims 2-13 are dependent on claim 1 and as such also meet the requirements of the PCT with respect to novelty and inventive step.

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### Claims

A capping unit for closing containers (2) with 1) the type comprising: of (3), respective caps component (5) on which to and conveyor carrier advance the containers (2) and the relative caps (3); a motor (6) associated with the carrier and conveyor component (5), by which the selfsame component (5) is set in rotation about a respective primary axis (5a); a plurality of capping assemblies (11) associated with the carrier component (5), each positioned above a corresponding container (2) and capable of movement vertically between a first position, distanced from the respective container (2), and a second position actively engaging the container, wherein each capping assembly (11) presents a gripping mechanism (17) such as can be associated with a relative cap (3) when the corresponding capping assembly (11) is in the second gripping mechanism (17)the position, and rotatable in such a way as to screw the cap (3) onto a threaded neck (4) of the respective container (2) about a respective secondary axis (17a); first drive means (14) presenting a plurality of primary electric motors (14a), each one of which associated with a respective capping assembly (11) by which the single be set in motion assemblies can (11)capping second independently of another; one vertically, drive means (18) presenting a plurality of secondary electric motors (18a), each one of which associated with a respective gripping mechanism (17) by which

the single gripping mechanisms (17) can be set in rotation one independently of another; and an electronic controller device (40) connected to each of the primary electric motors (14a) and the secondary electric motors (18a); characterized in that it further comprises a processing block (41) by means of which to vary the operating parameters of each primary electric motor (14a) and each secondary electric motor (18a) according to the dimensions of the respective containers (2).

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- 2) A unit as in claim 1, wherein the carrier component (5) comprises:
- a drum (8) associated with the motor (6) and rotatable about the primary axis (5a);
- a base (9) associated with the bottom of the drum (8), on which to stand the containers (2);
  - a platform (10), associated with the top of the drum (8) and facing the base (9), to which the capping assemblies (11) are mounted in a circumferential formation.
    - 3)A unit as in claim 2, wherein each capping assembly (11) comprises a rod (12) inserted slidably through a relative guide (13) afforded by the platform (10), extending longitudinally in coaxial alignment with

the secondary axis (17a) and presenting a first end (12a) with which the respective gripping mechanism (17) is associated, and a second end (12b) opposite to the first end (12a).

4) A unit as in claim 3, wherein each primary electric motor (14a) occupies a position coinciding with the second end (12b) of the rod (12) and above the platform (10).

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5)A unit as in claim 4, wherein each primary electric motor (14a) comprises a shaft (15) rotatable about a respective axis perpendicular to the secondary axis (17a), and a gear (15a) keyed to the shaft (15).

6)A unit as in claim 5, wherein each rod (12) presents a rack (16) extending longitudinally along the respective second end (12b) and engaged in meshing contact by the gear (15a) of each primary electric motor (14a), in such a way that the rod (12) can be set in motion vertically by rotation of the gear (15a).

7) A unit as in claims 3 to 6, wherein each secondary electric motor (18a) is mounted between the first end (12a) of the corresponding rod (12) and the gripping mechanism (17) and presents a shaft (19) rotatable about an axis parallel to the secondary axis (17a).

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- 8)A unit as in claim 7, wherein the gripping mechanism (17) comprises:
- a gripper (20) attached to the shaft (19) of the respective secondary electric motor (18a), capable of movement between an open condition in which the relative capping assembly (11) is in the first position and a closed condition in which the relative capping assembly (11) is in the second position with the gripper (20) engaging the relative cap (3);
- an actuator (25) by which the gripper (20) is caused to alternate between the open and closed conditions;
  - a transmission component (31) interposed between the gripper (20) and the actuator (25), by which motion is relayed from the actuator (25) to the gripper (20).
  - 9)A unit as in claim 8, wherein the gripper (20) comprises:
  - a carrier element (21) of substantially cylindrical appearance, associated coaxially with the shaft (19) of the secondary electric motor (18a);
    - a plurality of jaws (22) hinged circumferentially to the cylindrical carrier element (21) and capable

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of movement between a position drawn toward one another, corresponding to the closed condition of the gripper (20), and a position spread apart from one another, corresponding to the open condition of the gripper (20).

10)A unit as in claim 9, wherein each jaw (22) presents a substantially curved appearance and is identifiable as having a first end (22a) furnished with a following roller (23), a second end (22b) opposite to the first end (22a), furnished with a contact element (24) designed to engage the cap (3), and an intermediate portion (22c) disposed between the first end (22a) and the second end (22b) and hinged to carrier element (21).

- 11) A unit as in claim 8, wherein each transmission component (31) comprises a plunger (32) of substantially frustoconical geometry coaxially encircling and slidable along the shaft (19) of the secondary electric motor (18a), and a mechanical linkage (33) coupled rigidly to the plunger (32).
  - 12)A unit as in claim 11, wherein the plunger (32) presents a downwardly tapering outer surface (32c), and the following roller (23) of each jaw (22) rolls vertically on the selfsame external surface (32c).
- 25 13)A unit as in claim 11, wherein the actuator (25) is a linear actuator coupled to the mechanical

linkage (33) in such a way as to induce a vertical movement of the plunger (32).